



Moment of a couple

A couple is defined as a two parallel forces that have the same magnitude, but opposite directions, and are separated by a perpendicular distance d (fig 4-25). The moment produced by a couple is called a couple moment.

Scalar Formulation: The moment of a couple **M** (fig 4-27), is defined as having a magnitude of: M = F d

Where F is the magnitude of one of the forces and d is the perpendicular distance or moment arm between the forces. The direction and sense of the couple moment are determined by the right hand rule. **M** will act perpendicular to the plane containing these forces.

Vector Formulation: The moment of a couple can also be expressed by the vector Cross product as:

 $\mathbf{M} = \mathbf{r}_B \mathbf{x} \mathbf{F} + \mathbf{r}_A \mathbf{x} - \mathbf{F} = (\mathbf{r}_B - \mathbf{r}_A) \mathbf{x} \mathbf{F}$

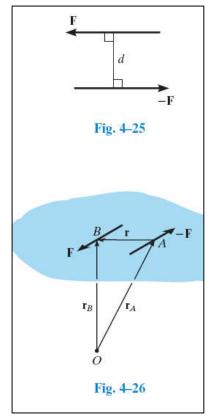
However, $\mathbf{r}_B = \mathbf{r}_A + \mathbf{r}$ or $\mathbf{r} = \mathbf{r}_B - \mathbf{r}_A$, so that:

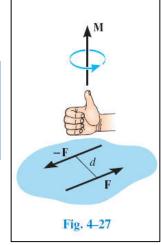
<mark>M = r</mark> x F

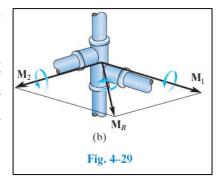
Note: This result indicates that a couple moment is a free vector, i.e., it can act at any point since M depends only upon the position vector \mathbf{r} directed between the forces and not the position vectors \mathbf{r}_A and \mathbf{r}_B , directed from the arbitrary point O to the forces.

Equivalent Couples. If two couples produce a moment with the *same magnitude and direction*, then these two couples are *equivalent*.

Resultant Couple Moment. Since couple moments are vectors, their resultant can be determined by vector addition. For example, consider the couple moments M_1 and M_2 acting on the pipe in Fig. 4–29 a. Since each couple moment is a free vector, we can join their tails at any arbitrary point and find the resultant couple moment, $M_R = M_1 + M_2$ as shown in Fig. 4–29 b.



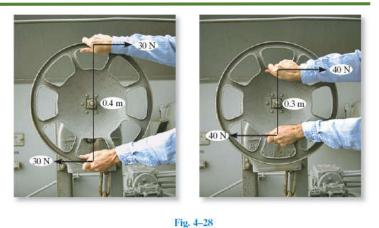








Equivalent Couples: If two couples produce a moment with the *same magnitude and direction*, then these two couples are *equivalent*. For example, the two couples shown in Fig. 4–28 are *equivalent* because each couple moment has a magnitude of:



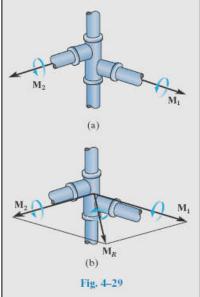
M = 30 N(0.4 m)

= 40 N(0.3 m) = 12 N.m, and each

is directed into the plane of the page. Notice that larger forces are required in the second case to create the same turning effect because the hands are placed closer together.

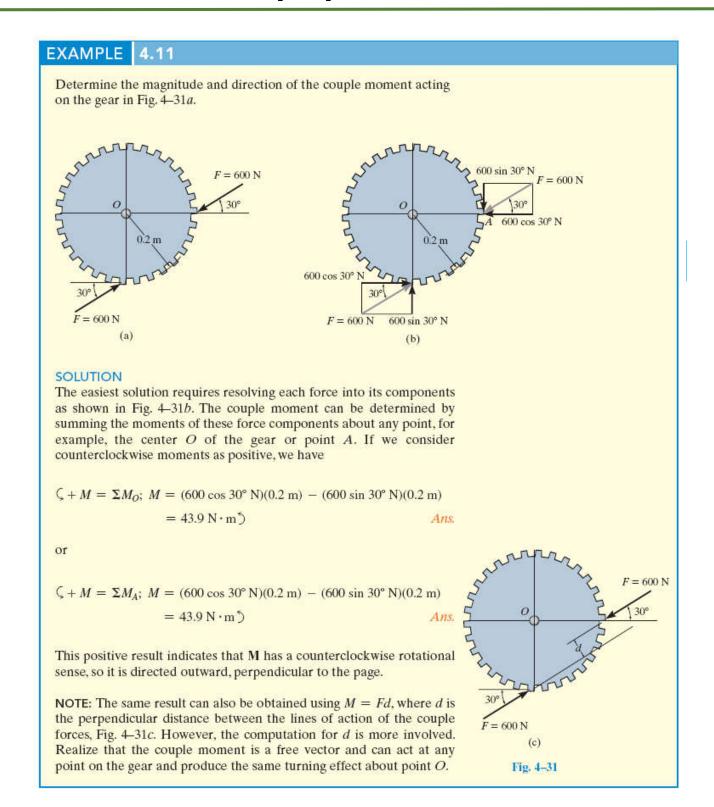
Resultant Couple Moment: Since couple moments are vectors, their resultant can be determined by vector addition. For example, consider the couple moments M_1 and M_2 acting on the pipe in Fig. 4–29 *a*. Since each couple moment is a free vector, we can join their tails at any arbitrary point and find the resultant couple moment, $M_R = M_1 + M_2$ as shown in Fig. 4–29 *b*. If more than two couple moments act on the body, we may generalize this concept and write the vector resultant as:

 $\mathbf{M}_R = \Sigma(\mathbf{r} \ge \mathbf{F})$



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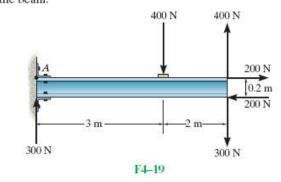




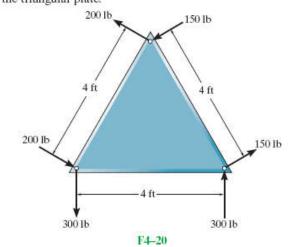


FUNDAMENTAL PROBLEMS

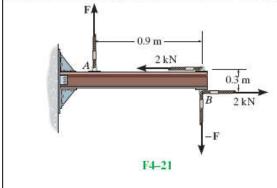
F4-19. Determine the resultant couple moment acting on the beam.



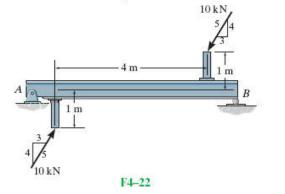
F4-20. Determine the resultant couple moment acting on the triangular plate.



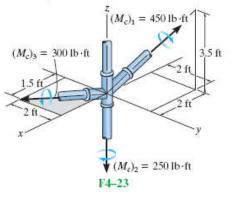
F4–21. Determine the magnitude of F so that the resultant couple moment acting on the beam is $1.5 \text{ kN} \cdot \text{m}$ clockwise.



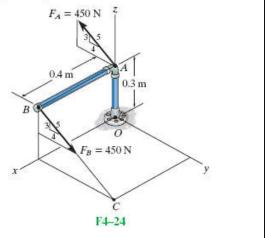
F4-22. Determine the couple moment acting on the beam.



F4-23. Determine the resultant couple moment acting on the pipe assembly.

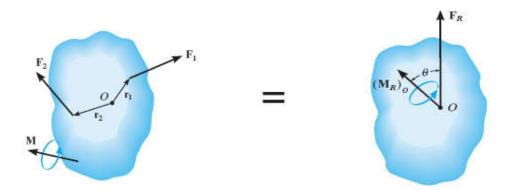


F4-24. Determine the couple moment acting on the pipe assembly and express the result as a Cartesian vector.





System of Forces and Couple Moments: Using the above method, a system of several forces and couple moments acting on a body can be reduced to an equivalent single resultant force (F_R) acting at a point *O* and a resultant couple moment (M_R)_O.



We can generalize the above method of reducing a force and couple system to an equivalent resultant force \mathbf{F}_R acting at point *O* and a resultant couple moment $(\mathbf{M}_R)_O$ by using the following two equations:

 $\mathbf{F}_{R} = \Sigma \mathbf{F}$ $(\mathbf{M}_{R})_{O} = \Sigma \mathbf{M}_{O} + \Sigma \mathbf{M}$

If the force system lies in the x - y plane and any couple moments are perpendicular to this plane, then the above equations reduce to the following three scalar equations:

$$(F_R)_x = \Sigma F_x$$

$$(F_R)_y = \Sigma F_y$$

$$(M_R)_O = \Sigma M_O + \Sigma M$$

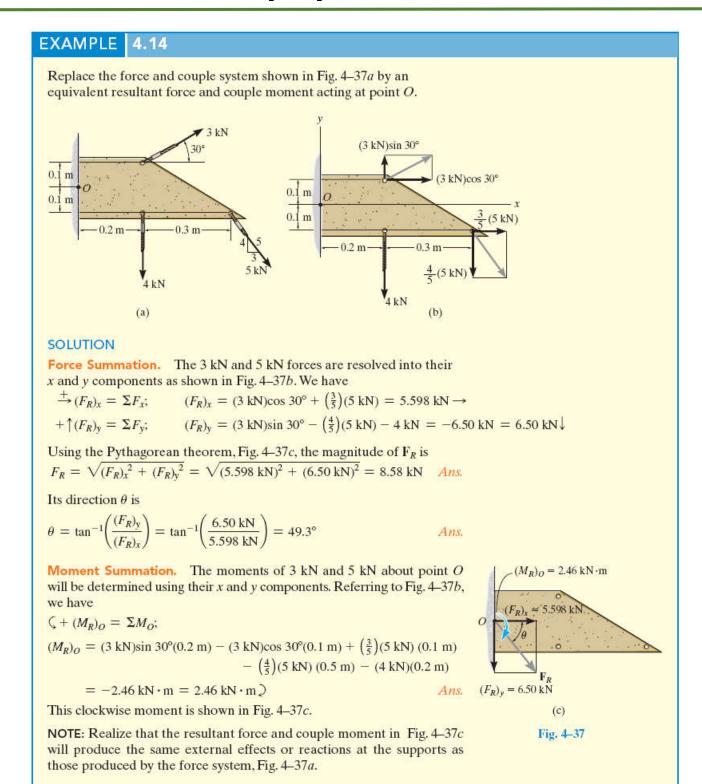
Where:

 ΣM = the sum of all the couple moments.

 ΣM_O = the sum of the moments of all the forces about point *O*.

• Here the resultant force is determined from the vector sum of its two components $(F_R)_x$ and $(F_R)_y$.





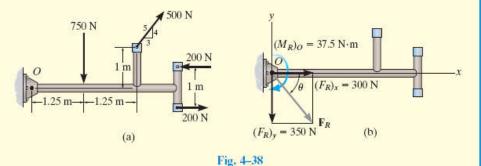
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Engineering Mechanics - STATICS

EXAMPLE 4.15

Replace the force and couple system acting on the member in Fig. 4-38a by an equivalent resultant force and couple moment acting at point O.



SOLUTION

Force Summation. Since the couple forces of 200 N are equal but opposite, they produce a zero resultant force, and so it is not necessary to consider them in the force summation. The 500-N force is resolved into its x and y components, thus,

$$\stackrel{+}{\to} (F_R)_x = \Sigma F_x; \ (F_R)_x = \left(\frac{3}{5}\right)(500 \text{ N}) = 300 \text{ N} \rightarrow + \uparrow (F_R)_y = \Sigma F_y; \ (F_R)_y = (500 \text{ N})\left(\frac{4}{5}\right) - 750 \text{ N} = -350 \text{ N} = 350 \text{ N} \downarrow$$

From Fig. 4–15*b*, the magnitude of F_R is

$$F_R = \sqrt{(F_R)_x^2 + (F_R)_y^2}$$

= $\sqrt{(300 \text{ N})^2 + (350 \text{ N})^2} = 461 \text{ N}$ Ans.

And the angle θ is

$$\theta = \tan^{-1} \left(\frac{(F_R)_y}{(F_R)_x} \right) = \tan^{-1} \left(\frac{350 \text{ N}}{300 \text{ N}} \right) = 49.4^{\circ}$$
 Ans.

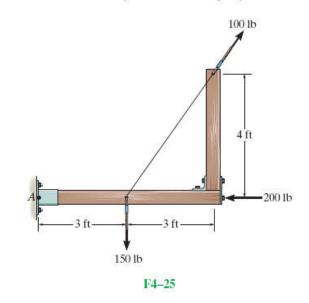
Moment Summation. Since the couple moment is a free vector, it can act at any point on the member. Referring to Fig. 4–38*a*, we have

This clockwise moment is shown in Fig. 4-38b.

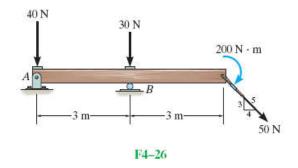


FUNDAMENTAL PROBLEMS

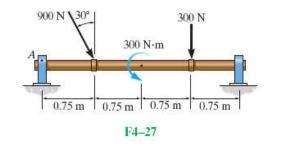
F4-25. Replace the loading system by an equivalent resultant force and couple moment acting at point A.



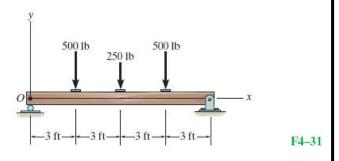
F4–26. Replace the loading system by an equivalent resultant force and couple moment acting at point A.



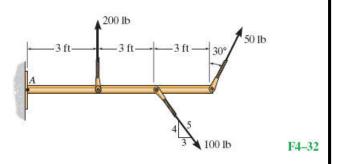
F4–27. Replace the loading system by an equivalent resultant force and couple moment acting at point *A*.



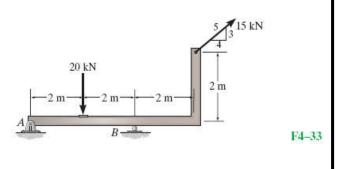
F4–31. Replace the loading system by an equivalent resultant force and specify where the resultant's line of action intersects the beam measured from O.



F4-32. Replace the loading system by an equivalent resultant force and specify where the resultant's line of action intersects the member measured from A.



F4-33. Replace the loading system by an equivalent resultant force and specify where the resultant's line of action intersects the horizontal segment of the member measured from A.



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