## COLUMN BUCKLING ANALYSIS BY FINITE DIFFERENCE METHODS

The basic differential equation of beam -column is: $E I y^{i v}+P y^{\prime \prime}=q(x)$
This can be written in difference equation form, if we know that

$$
\begin{array}{ll}
\frac{d y}{d x}=\frac{y_{i+1}-y_{i-1}}{2 h} & \frac{d^{2} y}{d x^{2}}=\frac{y_{i+1}-2 y_{i}+y_{i-1}}{h^{2}} \\
\frac{d^{3} y}{d x^{3}}=\frac{y_{i+3}-y_{i+1}+y_{i-1}-y_{i-3}}{2 h^{3}} & \frac{d^{4} y}{d x^{4}}=\frac{y_{i+2}-4 y_{i+1}+6 y_{i}-4 y_{i-1}-y_{i-2}}{2 h^{3}} \\
\mathbf{i}-\mathbf{1} & \mathbf{i}
\end{array}
$$



$$
k_{n}=\frac{p L^{2}}{n^{2} E I} \quad \& \quad h=\frac{L}{n}
$$

Example: Use the F.D.M. to find $P_{c r}$ for the column shown in the Fig 6.

1. Assume $n=2$

$$
\begin{gathered}
y_{i+2}+\left(k_{n}-4\right) y_{i+1}+\left(6-2 k_{n}\right) y_{i}+\left(k_{n}-4\right) y_{i-1} \\
+y_{i-2}=0
\end{gathered}
$$

@ fixed end : $y_{i-2}=y_{i}$


Figure 3:Hinge- fixed ends column
@ hinge end : $y_{i+2}=-y_{i}$

$$
\begin{gathered}
y_{i}+0+\left(6-2 k_{n}\right) y_{i}+0-y_{i}=0 \\
\left(6-2 k_{n}\right) y_{i}=0 \rightarrow k_{n=3} \quad k_{n}=\frac{P L^{2}}{n^{2} E I} \rightarrow 3=\frac{P_{c r} \times L^{2}}{4 E I} \rightarrow P_{c r}=\frac{12 L^{2}}{E I}
\end{gathered}
$$

H.W.: Resolve the previous example

1. Using advantage of B.C.
2. assume $n=3 \& n=4$
H.W.: For the beam rest on elastic foundation knowing $k$ is subgrade reaction along the beam $(\mathrm{KN} / \mathrm{m})$. calculate $P_{c r}$ use $\mathrm{n}=2$.


## COLUMN BUCKLING ANALYSIS BY MATRIX METHODS

Consider a prismatic column shown in Figure 6. The axial strain of a point at a distance $y$ from the neutral axis is:

$$
\varepsilon_{x}=\frac{d u}{d x}-y \frac{d^{2} v}{d x^{2}}+\frac{1}{2}\left(\frac{d v}{d x}\right)^{2}
$$

where $u$ and $v$ are displacement components in the $x$ and $y$ directions, respectively, and
$d u / d x=$ axial strain;
$-y\left(d^{2} v\right) /\left(d x^{2}\right)=$ strain produced by curvature; and
$1 / 2[(d v) /(d x)]^{2}=$ nonlinear part of the axial strain.
With $d V=d A d x$, the element strain energy is

$$
U=\frac{1}{2} \int_{V} \varepsilon \sigma d V=\frac{1}{2} \int_{\ell} \int_{A} E \varepsilon_{x}^{2} d A d x
$$

where $E=$ modulus of elasticity.

$$
\int_{A} d A=A, \int_{A} y d A=0, \int_{A} y^{2} d A=I, \quad \text { and } \quad \int_{A} E \frac{d u}{d x} d A=P
$$

where $P$ is the axial force, positive in tension, leads the strain energy to be written:

$$
U=\frac{1}{2} \int_{0}^{\ell} E A\left(\frac{d u}{d x}\right)^{2} d x+\frac{1}{2} \int_{0}^{\ell} E I\left(\frac{d^{2} v}{d x^{2}}\right)^{2} d x+\frac{1}{2} \int_{0}^{\ell} P\left(\frac{d v}{d x}\right)^{2} d x
$$

The first integral in Eq. above yields the stiffness matrix for a bar element associated with the kinematic degrees of freedom u 1 and u 2 . The second integral yields the stiffness matrix for a beam element. The third integral sums the work done by the external load $P$ when differential elements dx are stretched by an amount $\left[(d v / d x)^{2} \times d x / 2\right]$ (there exists another interpretation of the third integral: a change in the potential energy of the applied load during buckling). The third integral leads to the derivation of the element geometric stiffness matrix $K$. The lateral displacement field $v$ of the beam and its derivative $d v / d x$ are:

$$
v=\lfloor N\rfloor\{\Delta\}
$$

$$
\frac{d v}{d x}=\frac{d\lfloor N\rfloor}{d x}\{\Delta\}=\lfloor G\rfloor\{\Delta\}
$$

where

$$
\begin{gathered}
\lfloor\Delta\rfloor=\left\lfloor\begin{array}{llll}
v_{1} & \theta_{1} & v_{2} & \theta_{2} \\
\lfloor
\end{array}\right. \\
\lfloor N\rfloor=\left\lfloor\begin{array}{llll}
1-\frac{3 x^{2}}{\ell^{2}}+\frac{2 x^{3}}{\ell^{3}} & x-\frac{2 x^{2}}{\ell}+\frac{x^{3}}{\ell^{2}} & \frac{3 x^{2}}{\ell^{2}}-\frac{2 x^{3}}{\ell^{3}} & -\frac{x^{2}}{\ell}+\frac{x^{3}}{\ell^{2}} \\
\lfloor G\rfloor=\left\lfloor-\frac{6 x}{\ell^{2}}+\frac{6 x^{2}}{\ell^{3}}\right. & 1-\frac{4 x}{\ell}+\frac{3 x^{2}}{\ell^{2}} & \frac{6 x}{\ell^{2}}-\frac{6 x^{2}}{\ell^{3}} & -\frac{2 x}{\ell}+\frac{3 x^{2}}{\ell^{2}}
\end{array}\right]
\end{gathered}
$$

The third integral is expanded as

$$
\frac{1}{2}\lfloor\Delta\rfloor\left[K_{G}\right]\{\Delta\}=\frac{1}{2}\lfloor\Delta\rfloor\left[P \int_{0}^{\ell}\{G\}[G] d x\right]\{\Delta\}
$$

Hence,

$$
\begin{gathered}
K_{\mathrm{G} 11}=P \int_{0}^{\ell}\left(-\frac{6 x}{\ell^{2}}+\frac{6 x^{2}}{\ell^{3}}\right)^{2} d x=\frac{6 P}{5} \\
K_{\mathrm{G} 12}=P \int_{0}^{\ell}\left(-\frac{6 x}{\ell^{2}}+\frac{6 x^{2}}{\ell^{3}}\right)\left(1-\frac{4 x}{\ell}+\frac{3 x^{2}}{\ell^{2}}\right) d x=\frac{P}{10}
\end{gathered}
$$

Other elements are evaluated likewise.

$$
K_{G}=\frac{P}{30 \ell}\left[\begin{array}{cccc}
36 & 3 \ell & -36 & 3 \ell \\
3 \ell & 4 \ell^{2} & -3 \ell & -\ell^{2} \\
-36 & -3 \ell & 36 & -3 \ell \\
3 \ell & -\ell^{2} & -3 \ell & 4 \ell^{2}
\end{array}\right]
$$

Example: Consider a propped (fixedpinned) column shown in Fig. 7. The prismatic column length is L. Using the numbering scheme, one obtains the following stiffness relationship: As the global coordinate system and the local coordinate system are identical, there is no need for coordinate transformation.
Let $\phi=A l^{2} / I$.
Superimposing element stiffness matrices of bar element and beam element, one obtains an element stiffness matrix for a two-dimensional frame element.


Figure 7: Column model, degrees-offreedom

$$
\begin{aligned}
& K_{E}^{(1)}=\frac{E I}{\ell^{3}} \begin{array}{r}
1 \\
\\
4 \\
3 \\
5
\end{array}\left[\begin{array}{cccccc}
\phi & & & & & \\
0 & 12 & & & & \\
6 & 6 \ell & 4 \ell^{2} & & & \\
-\phi & 0 & 0 & \phi & & \\
0 & -12 & -6 \ell & 0 & 12 & \\
0 & 6 \ell & 2 \ell^{2} & 0 & -6 \ell & 4 \ell^{2}
\end{array}\right] \\
& 4 \\
& 5 {\left[\begin{array}{cccccc}
\phi & & & & & \\
K_{E}^{(2)}=\frac{E I}{\ell^{3}} & 6 \\
7 \\
7 & 12 & & & & \\
8 \\
0 & 6 \ell & 4 \ell^{2} & & & \\
-\phi & 0 & 0 & \phi & & \\
0 & -12 & -6 \ell & 0 & 12 & \\
0 & 6 \ell & 2 \ell^{2} & 0 & -6 \ell & 4 \ell^{2}
\end{array}\right] }
\end{aligned}
$$

$$
\begin{aligned}
& K_{G}^{(2)}=-\frac{P}{\ell}^{6}{ }_{7}^{6}\left[\begin{array}{cccccc}
0 & & & & \\
0 & 6 / 5 & & & \\
8 & \ell / 10 & 2 \ell^{2} / 15 & & & \\
0 & 0 & 0 & 0 & & \\
0 & -6 / 5 & -\ell / 10 & 0 & 6 / 5 & \\
0 & \ell / 10 & -\ell^{2} / 30 & 0 & -\ell / 10 & 2 \ell^{2} / 15
\end{array}\right]
\end{aligned}
$$

The elastic stiffness matrices $K_{E}$ and the stability matrices $K_{G}$ can now be assembled, reduced, and rearranged, separating the degrees of freedom associated with the axial deformations and the flexural deformations, respectively. Assembling the element stiffness matrices to construct the structural stiffness matrix is of course to combine the element contribution to the global stiffness. Reducing the assembled stiffness matrix is necessary to eliminate the rigid body motion, thereby making the structural stiffness matrix nonsingular.

$$
K_{G}=-\frac{P}{\ell} \begin{gathered}
1 \\
3 \\
5 \\
6
\end{gathered}\left[\begin{array}{ccccc}
0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 \\
0 & 0 & 2 \ell^{2} / 15 & -\ell / 10 & -\ell^{2} / 30 \\
0 & 0 & -\ell / 10 & 12 / 5 & 0 \\
0 & 0 & -\ell^{2} / 30 & 0 & 4 \ell^{2} / 15
\end{array}\right]
$$

Noting that $K_{G}^{*}$ is equal to $K_{G}$ for $P=1$, one can set up the stability determinant $\left|K_{E}+\lambda K_{G}^{*}\right|=0$. This leads to

$$
\left|\begin{array}{ccccc}
\phi & -\phi & 0 & 0 & 0 \\
-\phi & 2 \phi & 0 & 0 & 0 \\
0 & 0 & 4 \ell^{2}-\frac{2}{15} \frac{\lambda \ell^{2}}{E I} & -6 \ell+\frac{1}{10} \frac{\lambda \ell^{3}}{E I} & 2 \ell^{2}+\frac{1}{30} \frac{\lambda \ell^{4}}{E I} \\
0 & 0 & -6 \ell+\frac{1}{10} \frac{\lambda \ell^{3}}{E I} & 24-\frac{12}{5} \frac{\lambda \ell^{2}}{E I} & 0 \\
0 & 0 & 2 \ell^{2}+\frac{1}{30} \frac{\lambda \ell^{4}}{E I} & 0 & 8 \ell^{2}-\frac{4}{15} \frac{\lambda \ell^{4}}{E I}
\end{array}\right|=0
$$

Let $\mu=\lambda \ell^{2} / E I$

$$
\left|\begin{array}{ccccc}
\phi & -\phi & 0 & 0 & 0 \\
-\phi & 2 \phi & 0 & 0 & 0 \\
0 & 0 & 2\left(2-\frac{\mu}{15}\right) & -6+\frac{\mu}{10} & 2+\frac{\mu}{30} \\
0 & 0 & -6+\frac{\mu}{10} & 12\left(2-\frac{\mu}{5}\right) & 0 \\
0 & 0 & 2+\frac{\mu}{30} & 0 & 4\left(2-\frac{\mu}{15}\right)
\end{array}\right|=0
$$

Expanding this determinant, one obtains a cubic equation in $\mu$

$$
3 \mu^{3}-220 \mu^{2}+3,840 \mu-14,400=0
$$

The lowest root of this equation is $\mu=5.1772 \Rightarrow 5.1772=\lambda \ell^{2} / E I$
Hence,

$$
\begin{aligned}
P_{c r} & =\frac{5.1772 E I}{\ell^{2}}=\frac{5.1772 E I}{(0.5 L)^{2}}=\frac{20.7088 E I}{L^{2}}=\frac{2.098 \pi^{2} E I}{L^{2}} \\
& =1.026 P_{\text {exact }}=1.026\left(\frac{20.19 E I}{L^{2}}\right)
\end{aligned}
$$

Considering the fact that only two elements were used to model the column, this ( $2.6 \%$ difference) is a fairly good performance.

