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The G-S Algorithm

Step 0: Formulate and assemble Y_{bus} in per unit

Step 1: Assign initial guesses to unknown voltage magnitudes and angles

 $|V_1|=1.0, \delta=0.0$

Step 2a: For Load Buses, find using (17) V_i .

$$V_i^{(m+1)} = \frac{1}{Y_{ii}} \left[\frac{P_i - jQ_i}{V_i^{(m)*}} - \sum_{\substack{k=1\\k\neq i}}^n Y_{ik} \cdot V_k^{\beta} - \sum_{\substack{k=i+1\\k\neq i}}^n Y_{ik} \cdot V_k^{(m)} \right]$$

$$\beta = m \text{ for } k > i, \beta = m + 1 \text{ for } k < i$$

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where, m = iteration number. For generator bus, find using (11) and (17) together. That is, find Qi first.

$$Q_i^{(m+1)} = -\operatorname{Im} ag[V_i^{*(m)}\{V_i^{(m)}Y_{ii} + \sum_{k=1}^n Y_{ik}V_k^{(m)}]$$

Then

$$V_i^{(m+1)} = \frac{1}{Y_{ii}} \left[\frac{P_i - jQ_i}{V_i^{(m)*}} - \sum_{\substack{k=1\\k\neq i}}^n Y_{ik} \cdot V_k^{\beta} - \sum_{\substack{k=i+1\\k\neq i}}^n Y_{ik} \cdot V_k^{(m)} \right]$$

However, V_i is specified for generator busses. So:

$$V_i^{(m+1)} = \left| V_{i,spec} \right| \angle \delta_{icalc}^{(m+1)}$$

So, for example, if there are five busses in the system being studied, and one has determined new values of bus voltages at busses 1-3, then during the determination of bus voltage at bus 4, one should use these newly calculated values of bus voltages at 1, 2, and 3; busses 4 and 5 will have the values from the previous iteration.



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Step 2b: for faster convergence, apply acceleration factor to load buses

$$V_{i,acc}^{(m+1)} = V_{i,acc}^{(m)} + \alpha (V_i^{(m)} - V_{i,acc}^{(m)})$$

where α = acceleration factor.

Step 3: Check Convergence

$$|\operatorname{Re}[V_i^{(m+1)}] - |\operatorname{Re}[V_i^{(m)}] \le \varepsilon$$

That is, the absolute value of the difference of the real part of the voltage between successive iterations should be less than a tolerance value \mathcal{E} . Typically, $\mathcal{E} \leq 10^{-4}$, and also,

$$|\mathrm{Im} ag[V_i^{(m+1)}] - \mathrm{Im} ag[V_i^{(m)}] \le \varepsilon$$

That is, the absolute value of the difference of the imaginary value of the voltage should be less than a tolerance value ε ,



Figure : A two-bus system illustrating line-flow computation.

If the difference is greater than tolerance, return to Step 3. If the difference is less than tolerance, the solution has converged; go to Step 4.



Step 4: Find slack bus power Pg and Qg from equations (5) and (6).

Step 5: Find all line flows as described in the next section computing line flows. As the last step in any power-flow solution, one has to find the line flows. This is illustrated by the two-bus system shown in above Fig. Line current, Iij, at bus i is defined positive in the direction i to j.

$$I_{ik} = I_s + I_{pi} = (V_i - V_k) \cdot y_s + V_i \cdot y_{pi}$$

Let S_{kj} , S_{jk} be line powers defined positive into the line at bus i and j, respectively.

$$S_{ik} = P_{ik} + jQ_{ik} = V_i I_{ik}^* = V_i (V_i^* - V_k^*) \cdot y_s^* + |V_i|^2 \cdot y_{pi}^*$$
(a-1)
$$S_{ik} = P_{ik} + jQ_{ik} = V_i I_{ik}^* = V_i (V_i^* - V_j^*) \cdot y_s^* + |V_i|^2 \cdot y_{pi}^*$$
(a-2)

The power loss in line (i-j) is the algebraic sum of the power flows determined from (a-1) and (a-2).

$$S_{Lij} = S_{ij} + S_{ji}$$

Flowchart for Gauss-Sediel iterative method for load flow solution

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