### 1.6 PLANES IN 3-SPACE

### 1.6.1 Planes Parallel to the Coordinate Planes

Based on below figure,
The graph of $x=a$ is the plane through $(\mathrm{a}, 0,0)$ that is parallel to the $y z$-plane,
The graph of $y=b$ is the plane through $(0, b, 0)$ that is parallel to the $x z$-plane,
The graph of $z=c$ is the plane through $(0,0, c)$ that is parallel to the $x y$-plane.


### 1.6.2 Planes Determined by a Point and a Normal Vector

- A plane in 3-space can be determined uniquely by specifying a point in the plane and a vector perpendicular to the plane (see figure). A vector perpendicular to a plane is called a normal to the plane.
- Suppose that we want to find an equation of the plane passing through $P_{0}\left(x_{0}, y_{0}, z_{0}\right)$ and perpendicular to the vector $\mathbf{n}=(a, b, c)$. Define the vectors $\mathbf{r}_{0}$ and $\mathbf{r}$ as

$$
\mathbf{r}_{0}=\left(x_{0}, y_{0}, z_{0}\right) \text { and } \mathbf{r}=(x, y, z)
$$

- It should be evident from Figure that the plane consists precisely of those points $P(x, y, z)$ for which the vector $\mathbf{r}-\mathbf{r}_{0}$ is orthogonal to $\mathbf{n}$; or, expressed as an equation,

$$
\mathbf{n} .\left(\mathbf{r}-\mathbf{r}_{0}\right)=0
$$

If preferred, we can express this vector equation in terms of components as

$$
(a, b, c) \cdot\left(x-x_{0}, y-y_{0}, z-z_{0}\right)=0
$$

from which we obtain


The colored plane is determined uniquely by the point $P$ and the vector $\mathbf{n}$ perpendicular to the plane.


$$
a\left(x-x_{0}\right)+b\left(y-y_{0}\right)+c\left(z-z_{0}\right)=0
$$

This is called the point-normal form of the equation of a plane.

Example: Find an equation of the plane passing through the point $(3,-1,7)$ and perpendicular to the vector $\mathbf{n}=(4,2,-5)$.

Solution: a point-normal form of the equation is

$$
\begin{aligned}
& 4(x-3)+2(y+1)-5(z-7)=0 \\
& (4,2,-5) \cdot(x-3, y+1, z-7)=0
\end{aligned}
$$

we obtain an equation of the form

$$
\begin{aligned}
& a x+b y+c z+d=0 \\
& 4 x+2 y-5 z+25=0
\end{aligned}
$$

The following theorem shows that every equation represents a plane in 3-space.

## Theorem

If $a, b, c$, and $d$ are constants, and $a, b$, and $c$ are not all zero, then the graph of the equation

$$
a x+b y+c z+d=0
$$

is a plane that has the vector $\mathbf{n}=(a, b, c)$ as a normal.
Example: Determine whether the planes $3 x-4 y+5 z=0$ and $-6 x+8 y-10 z-4=0$ are parallel.
Solution: It is clear geometrically that two planes are parallel if and only if their normals are parallel vectors. A normal to the first plane is

$$
\mathbf{n}_{1}=(3,-4,5)
$$

and a normal to the second plane is

$$
\mathbf{n}_{2}=(-6,8,-10)
$$

Since $\mathbf{n}_{2}$ is a scalar multiple of $\mathbf{n}_{1}$, the normals are parallel, and hence so are the planes.
Example: Find an equation of the plane through the points $P_{1}(1,2,-1), P_{2}(2,3,1)$, and $P_{3}(3,-1,2)$.
Solution: Since the points $P_{1}, P_{2}$, and $P_{3}$ lie in the plane, the vectors $\overrightarrow{P_{1} P_{2}}=(1,1,2)$ and $\overrightarrow{P_{1} P_{3}}=(2,-3,3)$ are parallel to the plane. Therefore,

$$
\overrightarrow{P_{1} P_{2}} \times \overrightarrow{P_{1} P_{3}}=\left|\begin{array}{ccc}
\mathbf{i} & \mathbf{j} & \mathbf{k} \\
1 & 1 & 2 \\
2 & -3 & 3
\end{array}\right|
$$

is normal to the plane, since it is orthogonal to both $\overrightarrow{P_{1} P_{2}}$ and $\overrightarrow{P_{1} P_{3}}$. By using this normal and the point $P_{1}(1,2,-1)$ in the plane, we obtain the point-normal form

$$
9(x-1)+(y-2)-5(z+1)=0
$$

which can be rewritten as

$$
9 x+y-5 z-16=0
$$

Example: Determine whether the line $x=3+8 t, y=4+5 t, z=-3-t$ is parallel to the plane $x-3 y+5 z=12$.

Solution: The vector $\mathbf{v}=(8,5,-1)$ is parallel to the line and the vector $\mathbf{n}=(1,-3,5)$ is normal to the plane. For the line and plane to be parallel, the vectors $\mathbf{v}$ and $\mathbf{n}$ must be orthogonal. But this is not so, since the dot product $\mathbf{v} \cdot \mathbf{n}=(8)(1)+(5)(-3)+(-1)(5)=-12$ is nonzero. Thus, the line and plane are not parallel. ( $\mathbf{v} \cdot \mathbf{n}=0$ then right angle)

Example: Find the intersection of the line and plane in the previous example.
Solution: If we let $\left(x_{0}, y_{0}, z_{0}\right)$ be the point of intersection, then the coordinates of this point satisfy both the equation of the plane and the parametric equations of the line. Thus,

$$
\begin{equation*}
x_{0}-3 y_{0}+5 z_{0}=12 \tag{1}
\end{equation*}
$$

and for some value of $t$, say $t=t_{0}$,

$$
\begin{equation*}
x_{0}=3+8 t_{0}, y_{0}=4+5 t_{0}, z_{0}=-3-t_{0} \tag{2}
\end{equation*}
$$

Substituting (2) in (1) yields

$$
\left(3+8 t_{0}\right)-3\left(4+5 t_{0}\right)+5\left(-3-t_{0}\right)=12
$$

Solving for $t_{0}$ yields $t_{0}=-3$ and on substituting this value in (2), we obtain

$$
\left(x_{0}, y_{0}, z_{0}\right)=(-21,-11,0)
$$

### 1.6.3 Intersecting Planes

- Two distinct intersecting planes determine two positive angles of intersection-an (acute) angle $\theta$ that satisfies the condition $0 \leq \theta \leq \pi / 2$ and the supplement of that angle (Figure $a$ ).
- If $\mathbf{n}_{1}$ and $\mathbf{n}_{2}$ are normals to the planes, then depending on the directions of $\mathbf{n}_{1}$ and $\mathbf{n}_{2}$, the angle $\theta$ is either the angle

(a)

(b)

Example: Find the acute angle of intersection between the two planes $2 x-4 y+4 z=6$ and $6 x+2 y-3 z=4$

Solution: The given equations yield the normals $\mathbf{n}_{1}=(2,-4,4)$ and $\mathbf{n}_{2}=(6,2,-3)$.

$$
\begin{gathered}
\cos \theta=\frac{\left|\mathbf{n}_{1} \cdot \mathbf{n}_{2}\right|}{\left\|\mathbf{n}_{1}\right\|\left\|\mathbf{n}_{2}\right\|}=\frac{|-8|}{\sqrt{36} \sqrt{49}}=\frac{4}{21} \\
\theta=\cos ^{-1}\left(\frac{4}{21}\right) \approx 79^{\circ}
\end{gathered}
$$

### 1.6.4 Distance Problems Involving Planes

Considering three basic distance problems in 3-space:
a. Find the distance between a point and a plane.
b. Find the distance between two parallel planes.
c. Find the distance between two skew lines.

(a)

## Theorem

The distance $D$ between a point $P_{0}\left(x_{0}, y_{0}, z_{0}\right)$ and the plane $a x+$ by $+c z+d=0$ is

$$
D=\frac{a x_{0}+b y_{0}+c z_{0}+d}{\sqrt{a^{2}+b^{2}+c^{2}}}
$$


(b)

Example: Find the distance $D$ between the point $(1,-4,-3)$ and the plane $2 x-3 y+6 z=-1$

Solution: the plane be rewritten in the form $a x+b y+c z+d=0$.
Thus, we rewrite the equation of the given plane as

$$
2 x-3 y+6 z+1=0
$$

from which we obtain $a=2, b=-3, c=6$, and $d=1$.

$$
D=\frac{|(2)(1)+(-3)(-4)+6(-3)+1|}{\sqrt{2^{2}+(-3)^{2}+6^{2}}}=\frac{|-3|}{7}=\frac{3}{7}
$$

Example: The planes $x+2 y-2 z=3$ and $2 x+4 y-4 z=7$ are parallel since their normals, ( 1 , $2,-2)$ and $(2,4,-4)$, are parallel vectors. Find the distance between these planes.

Solution: To find the distance $D$ between the planes, we can select an arbitrary point in one of the planes and compute its distance to the other plane. By setting $y=z=0$ in the equation $x+2 y-2 z=3$, we obtain the point $P_{0}(3,0,0)$ in this plane.
The distance from $P_{0}$ to the plane $2 x+4 y-4 z=7$ is

$$
D=\frac{|(2)(3)+4(0)+(-4)(0)-7|}{\sqrt{2^{2}+4^{2}+(-4)^{2}}}=\frac{1}{6}
$$

Example: It was shown in previous example that the lines $L_{1}: x=1+4 t, y=5-4 t, z=-1+$ $5 t \quad L_{2}: x=2+8 t, y=4-3 t, z=5+t$ are skew. Find the distance between them.

Solution: Let $P_{1}$ and $P_{2}$ denote parallel planes containing $L_{1}$ and $L_{2}$, respectively (see figure).

- To find the distance $D$ between $L_{1}$ and $L_{2}$, we will calculate the distance from a point in $P 1$ to the plane $P_{2}$.
- Since $L_{1}$ lies in plane $P_{1}$, we can find a point in $P_{1}$ by finding a point on the line $L_{1}$; we can do this by substitut-
 ing any convenient value of $t$ in the parametric equations of $L_{1}$. The simplest choice is $t=0$, which yields the point $Q_{1}(1,5,-1)$.
- The next step is to find an equation for the plane $P_{2}$. For this purpose, observe that the vector $\mathbf{u}_{1}=(4,-4,5)$ is parallel to line $L_{1}$, and therefore also parallel to planes $P_{1}$ and $P_{2}$.
- $\quad$ Similarly, $\mathbf{u}_{2}=(8,-3,1)$ is parallel to $L_{2}$ and hence parallel to $P_{1}$ and $P_{2}$. Therefore, the cross product

$$
\mathbf{n}=\mathbf{u}_{1} \times \mathbf{u}_{2}=\left|\begin{array}{rrr}
\mathbf{i} & \mathbf{j} & \mathbf{k} \\
4 & -4 & 5 \\
8 & -3 & 1
\end{array}\right|=11 \mathbf{i}+36 \mathbf{j}+20 \mathbf{k}
$$

is normal to both $P_{1}$ and $P_{2}$. Using this normal and the point $Q_{2}(2,4,5)$ found by setting $t=0$ in the equations of $L_{2}$, we obtain an equation for $P_{2}$ :

$$
11(x-2)+36(y-4)+20(z-5)=0
$$

or

$$
11 x+36 y+20 z-266=0
$$

The distance between $Q_{1}(1,5,-1)$ and this plane is

$$
D=\frac{|(11)(1)+(36)(5)+(20)(-1)-266|}{\sqrt{11^{2}+36^{2}+20^{2}}}=\frac{95}{\sqrt{1817}}
$$

### 1.7 QUADRIC SURFACES

- Although the general shape of a curve in 2-space can be obtained by plotting points, this method is not usually helpful for surfaces in 3 -space because too many points are required.
- It is more common to build up the shape of a surface with a network of mesh lines, which are curves obtained by cutting the surface with well-chosen planes.
- For example, the figure shows the graph of $z=x^{3}$ $3 x y^{2}$ rendered with a combination of mesh lines and colorization to produce the surface detail. This surface is called a "monkey saddle" ]].
- The mesh line that results when a surface is cut by a plane is called the trace of the surface in the plane (see figure).


A monkey saddle

(a)

(b

We noted that a second-degree equation

$$
A x^{2}+B x y+C y^{2}+D x+E y+F=0
$$

represents a conic section (possibly degenerate). The analog of this equation in an $x y z$ coordinate system is

$$
A x^{2}+B y^{2}+C z^{2}+D x y+E x z+F y z+G x+H y+I z+J=0
$$

which is called a second-degree equation in $x, y$, and $z$. The graphs of such equations are called quadric surfaces or sometimes quadrics.

Six common types of quadric surfaces are shown in the following table-ellipsoids, hyperboloids of one sheet, hyperboloids of two sheets, elliptic cones, elliptic paraboloids, and hyper-
bolic paraboloids. (The constants $a, b$, and $c$ that appear in the equations in the table are assumed to be positive.)

| surface | equation | surface | equation |
| :---: | :---: | :---: | :---: |
|  | $\frac{x^{2}}{a^{2}}+\frac{y^{2}}{b^{2}}+\frac{z^{2}}{c^{2}}=1$ <br> The traces in the coordinate planes are ellipses, as are the traces in thoce planes that are parallel to the coordinate planes and intersect the surface in more than one point. |  | $z^{2}=\frac{x^{2}}{a^{2}}+\frac{y^{2}}{b^{2}}$ <br> The trace in the $x y$-plase is a point (the origin), and the traces in plases parallel to the $x y$-plane are ellipoes. The traces in the $y$ and $x$-planss are pairs of lines inlarsecting of the origin. The traces in planes parallel to these are hyperbols. |
| $\square$ of one sheet | $\frac{x^{2}}{a^{2}}+\frac{y^{2}}{b^{2}}-\frac{z^{2}}{c^{2}}=1$ <br> The trace in the $x$-plane is an ellipse, as are the traces in plase parallel to the ry-plase. The traces in the ys-plane and $x z$-plase are hypertolus, wa are the traces in those planes that ans parallel to these and do not pass throogh the $x$ - or $y$-intereepts. At these intercepts the traces are pairs of intersecting linss. | Ellptic paraboloid | $z=\frac{x^{2}}{a^{2}}+\frac{y^{2}}{b^{2}}$ <br> The trace in the $x$-plane is a point (the origin), and the traces in plases parallel to and bove the ry-plase are ellipses. The traces in the $\pi$ - and $x<$-planes are parabolas, as are the traces in planes parallel to these. |
| HYPERBOLOID <br> OF TwO SHEETS | $\frac{z^{2}}{c^{2}}-\frac{x^{2}}{a^{2}}-\frac{y^{2}}{b^{2}}=1$ <br> There is no trace in the ry-plane In planes parallel to the $x y$-plane that intersest the surfice in more than ose point the traces are ellipses. In the $y$ - and $x$-plans, the trace are hypentolis, wa are the traces in those planes that and parallel to these. | hyperbolic paraholom | $z=\frac{y^{2}}{b^{2}}-\frac{x^{2}}{a^{2}}$ <br> The race in the $x y$-plane is a pair of lines intersecting at the origin. The traces in planes parallel to the $x y$-plane are hyperbolas. The hyperboles above the xy-plane open in the $y$-direction, and those belaw in thex-dirsction. The traces in the $y$ - and $x$-planes are parabolis, 2s are the traces in planes parallel to these. |

### 1.7.1 Techniques for Graphing Quadric Surfaces

A rough sketch of an ellipsoid

$$
\frac{x^{2}}{a^{2}}+\frac{y^{2}}{b^{2}}+\frac{z^{2}}{c^{2}}=1
$$

$$
(a>0, b>0, c>0)
$$

can be obtained by first plotting the intersections with the coordinate axes, and then sketching the elliptical traces in the coordinate planes.

Example: Sketch the ellipsoid

$$
\frac{x^{2}}{4}+\frac{y^{2}}{16}+\frac{z^{2}}{9}=1
$$

Solution: The $x$-intercepts can be obtained by setting $y=0$ and $z=0$ in. This yields $x= \pm 2$. Similarly, the $y$-intercepts are $y=$ $\pm 4$, and the $z$-intercepts are $z= \pm 3$. Sketching the elliptical traces in the coordinate planes yields the graph in the figure.


Example: Sketch the graph of the hyperboloid of one sheet

$$
x^{2}+y^{2}-\frac{z^{2}}{4}=1
$$

Solution: The trace in the $x y$-plane, obtained by setting $z=0$, is

$$
x^{2}+y^{2}=1(z=0)
$$

which is a circle of radius 1 centered on the $z$-axis. The traces in the planes $z=2$ and $z=-2$, obtained by setting $z= \pm 2$, are given by

$$
x^{2}+y^{2}=2(z= \pm 2)
$$

which are circles of radius $\sqrt{2}$ centered on the $z$-axis. Joining these circles by the hyperbolic traces in the vertical coordinate
 planes yields the graph in the following figure.
Example: Sketch the graph of the hyperboloid of two sheets

$$
z^{2}-x^{2}-\frac{y^{2}}{4}=1
$$

Solution: The z-intercepts, obtained by setting $x=0$ and $y=$ 0 , are $z= \pm 1$. The traces in the planes $z=2$ and $z=-2$, obtained by setting $z= \pm 2$ in (10), are given by

$$
\frac{x^{2}}{3}+\frac{y^{2}}{12}=1 \quad(z= \pm 2)
$$

Sketching these ellipses and the hyperbolic traces in the vertical coordinate planes yields the following figure.


