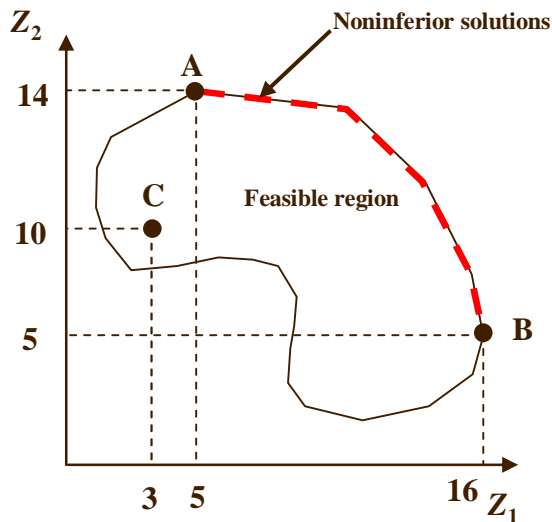


- move to the boundary by increasing one objective w/o decreasing another
- Northeast rule:
 - A feasible solution is noninferior if there are no feasible solutions lying to the northeast (when maximizing)



Alternative	Z_1	Z_2
A	5	14
B	16	5
C	3	10

\vec{x} is noninferior if there exists no feasible \vec{y} such that

$$Z_k(\vec{y}) \geq Z_k(\vec{x}) \quad k = 1, \dots, p$$

Maximize $\vec{Z}(\vec{x}) = [Z_1(\vec{x}), Z_2(\vec{x})]$

subject to

$$Z_1(\vec{x}) = 5x_1 - 2x_2$$

$$Z_2(\vec{x}) = -x_1 + 4x_2$$

(1) $-x_1 + x_2 \leq 3$

(2) $x_1 + x_2 \leq 8$

(3) $x_1 \leq 6$

(4) $x_2 \leq 4$

Tradeoffs

- Tradeoff = Amount of one objective sacrificed to gain an increase in another objective, i.e., to move from one noninferior solution to another
- Example: Tradeoff between Z1 and Z2 in moving from D to C is 14/10, i.e., 7/5 unit of Z1 is given up to gain 1 unit of Z2 and vice versa

$$\frac{\partial Z_i(\vec{x})}{\partial Z_j(\vec{x})}$$

Multiobjective Methods

- Information flow in the decision making process
 - Top down: Decision maker (DM) to analyst (A)
 - ✓ Preferences are sent to A by DM, then best compromise solution is sent by A to DM
 - ✓ Preference methods
 - Bottom up: A to DM
 - ✓ Noninferior set and tradeoffs are sent by A to DM
 - ✓ Generating methods
- Generating methods
 - Present a range of choice and tradeoffs among objectives to DM
 - ✓ Weighting method
 - ✓ Constraint method
 - ✓ Others
- Preference methods
 - DM must articulate preferences to A. The means of articulation distinguishes the methods
 - ✓ Noninteractive methods: Articulate preferences in advance
 - Goal programming method, Surrogate Worth Tradeoff method
 - ✓ Iterative methods: Some information about noninferior set is available to DM and preferences are updated
 - Step Method

Generating Techniques

- Weighting method

Mazimize $Z_1(\vec{x})$

subject to

$$g_1(\vec{x}) \leq b_1$$

⋮

$$g_m(\vec{x}) \leq b_m$$

$$\vec{x} = (x_1, x_2, \dots, x_n) \geq 0$$

Mazimize $Z(\vec{x}) = w_1 Z_1(\vec{x}) + w_2 Z_2(\vec{x}) + \dots + w_p Z_p(\vec{x})$

subject to

$$g_1(\vec{x}) \leq b_1$$

⋮

$$g_m(\vec{x}) \leq b_m$$

$$\vec{x} = (x_1, x_2, \dots, x_n) \geq 0$$



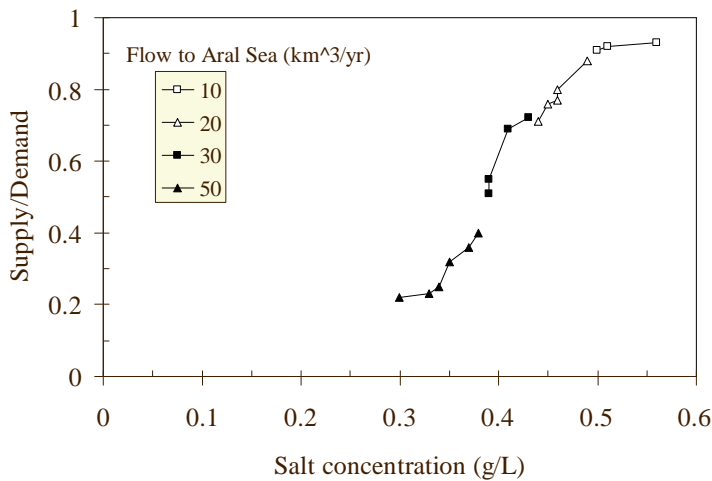
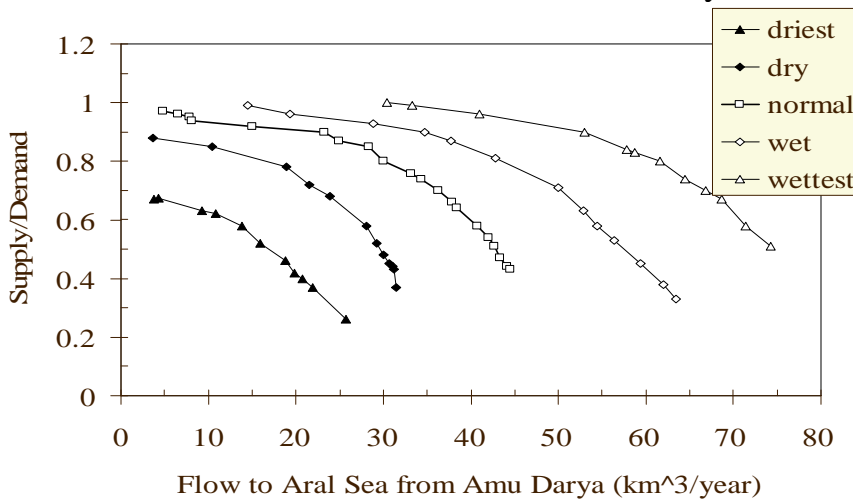
– Tradeoffs are explicit in the weights

$$-\frac{\partial Z_i(\vec{x})}{\partial Z_j(\vec{x})} = \frac{w_j}{w_i}$$

– Vary the weights over reasonable ranges to generate a wide range of alternative solutions reflecting different priorities.

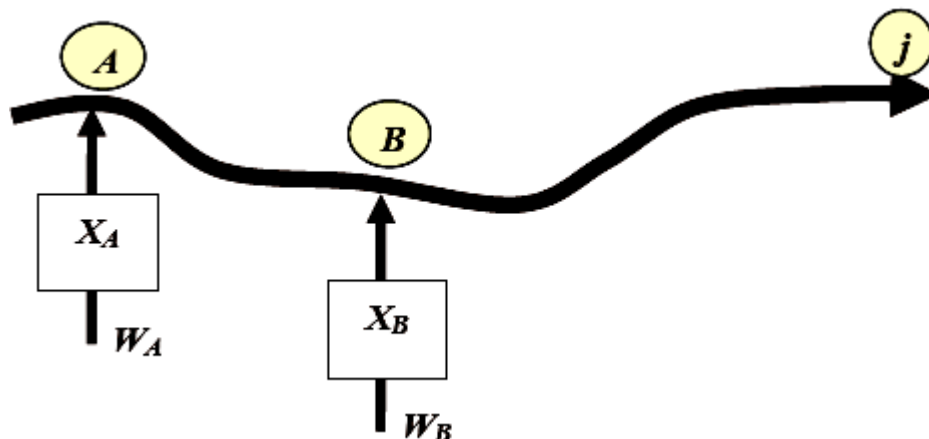
Example – Amu Darya River

- Multiple Objectives
 - Maximize water supply to irrigation
 - Maximize flow to the Aral Sea
 - Minimize salt concentration in the system



Example 1: Two waste dischargers, A and B, are located along a river and they can increase their waste treatment efficiencies, X_A and X_B , at costs $CA(X_A)$ and $CB(X_B)$, respectively. Let W_A and W_B be the untreated waste produced. The resulting waste discharges into the river at sites A and B must not exceed effluent standards E_A^{Max} and E_B . The resulting pollution concentration at various locations j in the river downstream of the discharge points must not exceed the stream standards S_j^{Max} . Let the pollutant concentration at location j be c_j . Further, let a_{ij} be a transfer coefficient describing the concentration at location j due to a unit input of pollutant upstream at point i ($i = A$ or B), and \hat{c}_j is the unregulated concentration at site j .

Assume that (1) the total cost of providing treatment and (2) any treatment cost inequity (the difference in cost between sites A and B) are water quality management objectives to be minimized simultaneously.



- (a) Define a non-inferior (or Pareto efficient) solution, i.e., state what characteristics a non-inferior solution has compared to an inferior solution.

SOLUTION

In principle if one has identified a noninferior solution, to increase the value of one objective, one has to accept less of another objective.

A feasible solution is **noninferior** if there exist no other feasible solutions that will yield an improvement in one objective without causing a decrease in at least one other objective

\vec{x} noninferio if there exists no feasible \vec{y} such that

$$Z_k(\vec{y}) \geq Z_k(\vec{x}) \quad k = 1, \dots, p$$

- (b) Show how you would model this multiobjective problem using the weighting approach. Does this formulation lead to a linear programming model? If not, then show how

it can be converted to a linear program.

SOLUTION

Minimize $W_1[C_A(X_A) + C_B(X_B)] + W_2|C_A(X_A) - C_B(X_B)|$

Subject to

$$W_A(1 - X_A) \leq E_A^{\max}$$

$$W_B(1 - X_B) \leq E_B^{\max}$$

$$c_j = a_{Aj}W_A(1 - X_A) + a_{Bj}W_B(1 - X_B) \leq S_j^{\max}$$

$$0 \leq X_A \leq 1$$

$$0 \leq X_B \leq 1$$

As written, the model is nonlinear because of the absolute value in the objective function. However, this can be linearized by defining some slack and surplus variables

Minimize $W_1[C_A(X_A) + C_B(X_B)] + W_2(D^{pos} + D^{neg})$

Subject to

$$C_A(X_A) - C_B(X_B) = D^{pos} - D^{neg}$$

$$W_A(1 - X_A) \leq E_A^{\max}$$

$$W_B(1 - X_B) \leq E_B^{\max}$$

$$c_j = a_{Aj}W_A(1 - X_A) + a_{Bj}W_B(1 - X_B) \leq S_j^{\max}$$

$$0 \leq X_A \leq 1$$

$$0 \leq X_B \leq 1$$

Example2: A reservoir is planned for irrigation and low flow augmentation for water quality control. A storage volume of 6 million m³ will be available for these two conflicting uses each year. The maximum irrigation demand is 4 million m³. Let X₁ be the allocation of water to irrigation and X₂ the allocation for downstream flow augmentation. Assume that there are two objectives, expressed as

$$Z_1(X) = 4X_1 - X_2$$

$$Z_2(X) = 2X_1 + 6X_2$$

