

Most important terms

Repair Mechanisms

Parameter Tuning

Single-Solution Based Metaheuristic (SBH)



Generate an initial Sol. (*S*) While Improvement is possible Do modifying and improving (*S*) Return (*S*)



Single-base Meta-heuristics - Generate an Initial Solution

Two main strategies are used to generate the initial solution:

Greedy strategy

- makes the locally best choice at each step
- reduced polynomial-time complexity.
- often leads to better quality local optima.
- less iterations to converge toward a local optimum.

Random strategy

- Generating a random initial solution is a quick operation.
- take much larger number of iterations to converge.

To improve the robustness, a <u>hybrid</u> <u>strategy</u> may be used. It consists in combining both: random and greedy.

Note1

using better solutions as initial solutions <u>does not</u> always lead to better local optima.

Note2

There is always a trade-off between the use of random and greedy initial solutions in terms of <u>the</u> <u>quality of solutions</u> and <u>the</u> <u>computational time</u> depend on the efficiency of the random and greedy algorithms and the SBH properties.

Ex: The larger is the neighborhood, the less is the sensitivity of the initial solution to the S-metaheuristics performance .

Neighborhood Structure The types of movements applied in local searches are called neighborhood functions or neighborhood structures because they access to neighboring solutions and define the size of the neighborhood.

The neighborhood structures have a prominent role in the performance of any SBH
The existence of adequate neighborhood leads to enhance the ability of a SBH to generate good solutions.

Zapfel, G., R. Braune & M. Bogl. 2010. Metaheuristic search concepts Ed.: Springer.

Neighbors of a solution are obtained via making minor changes to the solution using neighborhood structures or move operators

<u>Def.</u>

Search space is a directed graph G = (S,E), where the set of **vertices S** corresponds to the solutions of the problem that are defined by the representation (encoding) used to solve the problem, and the set of **edges E** corresponds to the move operators used to generate new solutions (neighborhood in SBH).

There is an edge e_{ij} between solutions S_i and S_j if the solution S_j can be generated from the solution S_i using a move operator; that is, S_i and S_j are neighbors.

Accepting Criteria

The acceptance criteria are one of the important components of the SBHs which determine the acceptance of the neighbor solution. <u>It has a significant role to escape</u> <u>from the local optima</u>.

A *local optimum* is a point in the search space where all neighboring solutions are worse than the current solution.

Burke, E. K. & G. Kendall. 2005. Search methodologies: introductory tutorials in optimization and decision support techniques Ed.: Springer.

Strategies can be applied in the selection of the Neighbor:

| Best improvement | First improvement | Random selection | Accept all solutions |
|---|--|---|---|
| whole neighborhood of the current solution is generated and the best neighboring solution is accepted | neighboring solutions are generated one by one until the first neighboring solution that improves the current solution is accepted | The whole neighborhood of the current solution is generated. Among all improving neighbors, a neighbor is randomly accepted. | Any generated solution is accepted regardless of its quality. This kind is adopted to diversify the search |

| Types of acceptance c | teria: | |
|--------------------------------------|--|--|
| Deterministic acceptance criteria | same decision is always returned no matter the initial and current solution. | |

| Non-deterministic acceptance criteria | Different decisions are usually returned even if the initial solution is the same. | |
|--|---|--|
| | Usually, in this kind of criteria, there are few parameters that have a significant impact on the acceptance or rejection the neighbor according to the acceptance probability. | |

Stopping Criteria

The important issue that should be taken into consideration when designing SBH is how to determine the termination criterion.

inappropriate choice of stopping criterion leads either to stopping the search process before finding the optimum solution or to causing waste of time.

The stopping criterion may depend on:

- > the maximum number of non-improving iterations.
- the maximum number of iterations.
- the maximum amount of running time.

Burke, E. K. & G. Kendall. 2005. Search methodologies: introductory tutorials in optimization and decision support techniques Ed.: Springer.



LOCAL SEARCH/ HILL CLIMBING

Local search algorithm.

```
s = s_0; /*Generate an initial solution s_0*/
```

While not Termination Criterion Do

Generate (N(s)); /*Generation of candidate neighbors*/

If there is no better neighbor Then Stop;

s = s'; /*Select a better neighbor $s' \in N(s)$ */

Endwhile

Output Final solution found (local optima).

search space.

In order to avoid becoming stuck at local optima, many alternatives algorithms have been proposed. Different families of approaches can be used to avoid local optima

SIMULATED ANNEALING

Simulated annealing algorithm.

Input: Cooling schedule.

s = s₀; /*Generation of the initial solution*/

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T = T<sub>max</sub>; /*Starting temperature*/
```

Repeat

Randomly generate a random neighbor s';

 $\Delta f = f(s') - f(s);$ /*For minimization problem*/

If $\Delta f \leq 0$ Then s = s'/*Accept the neighbor solution*/

Else Accept s' with a probability $e^{\frac{-\Delta f}{T}}$;

T = g(T) ; /*Temperature update*/

Until Stopping criteria is satisfied /*e.g. T < T_{min}*/

Output: Best solution found.

