DYNAMIC PROGRAMMING

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Dynamic Programming

Dynamic Programming **is a general algorithm design technique for solving problems defined by recurrences with overlapping subproblems**

- **Invented by American mathematician Richard Bellman in the 1950s to solve optimization problems and later assimilated by CS**

- **"Programming" here means "planning"**

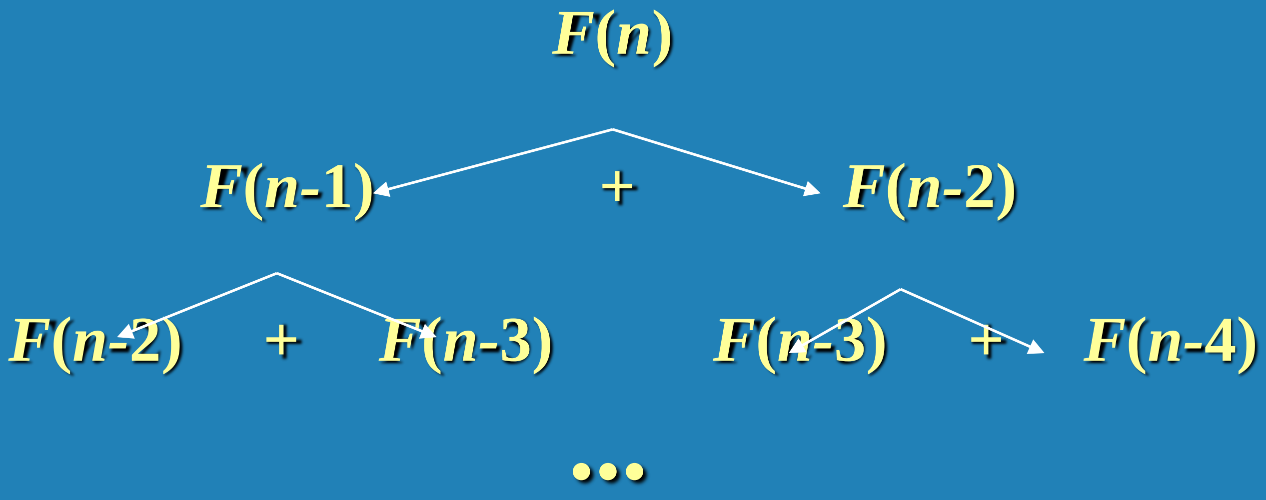
- **Main idea:**
  - **set up a recurrence relating a solution to a larger instance to solutions of some smaller instances**
  - **solve smaller instances once**
  - **record solutions in a table**
  - **extract solution to the initial instance from that table**

Example: Fibonacci numbers

- **Recall definition of Fibonacci numbers:**

$$F(n) = F(n\text{-}1) + F(n\text{-}2)$$
$$F(0) = 0$$
$$F(1) = 1$$

- **Computing the n^{th} Fibonacci number recursively (top-down):**



$F(n)$

$F(n\text{-}1) \quad + \quad F(n\text{-}2)$

$F(n\text{-}2) \quad + \quad F(n\text{-}3) \qquad F(n\text{-}3) \quad + \quad F(n\text{-}4)$

...

Example: Fibonacci numbers (cont.)

Computing the n^{th} Fibonacci number using bottom-up iteration and recording results:

$F(0) = 0$
$F(1) = 1$
$F(2) = 1+0 = 1$
…
$F(n-2) =$
$F(n-1) =$
$F(n) = F(n-1) + F(n-2)$

0	1	1	. . .	$F(n-2)$	$F(n-1)$	$F(n)$

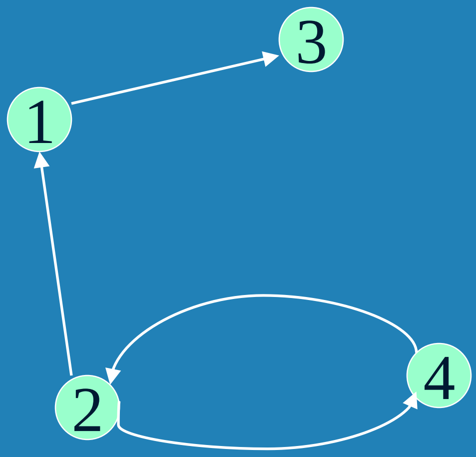
Efficiency:
- time
- space

Examples of DP algorithms

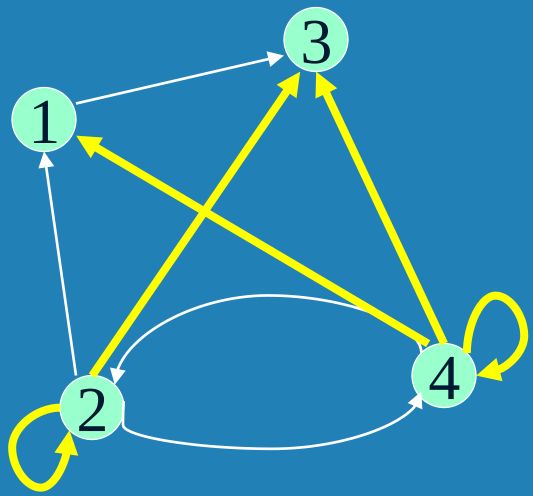
- Computing a binomial coefficient
- Warshall’s algorithm for transitive closure
- Floyd’s algorithm for all-pairs shortest paths
- Constructing an optimal binary search tree
- Some instances of difficult discrete optimization problems:
  - traveling salesman
  - knapsack

Warshall’s Algorithm: Transitive Closure

- Computes the transitive closure of a relation
- Alternatively: existence of all nontrivial paths in a digraph
- Example of transitive closure:



$$\begin{matrix} 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{matrix}$$



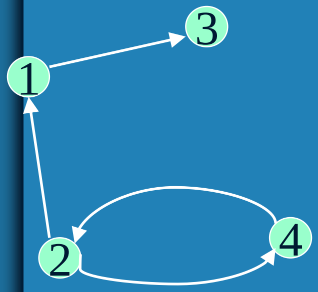
$$\begin{matrix} 0 & 0 & 1 & 0 \\ 1 & \mathbf{1} & \mathbf{1} & 1 \\ 0 & 0 & 0 & 0 \\ \mathbf{1} & 1 & \mathbf{1} & \mathbf{1} \end{matrix}$$

Warshall's Algorithm

Constructs transitive closure *T* as the last matrix in the sequence of *n*-by-*n* matrices $R^{(0)}, \ldots, R^{(k)}, \ldots, R^{(n)}$ where

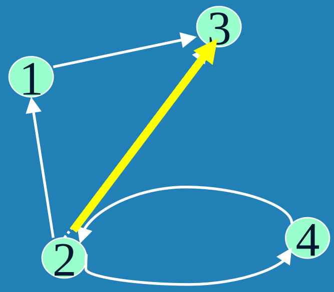
$R^{(k)}[i,j] = 1$ iff there is nontrivial path from *i* to *j* with only first *k* vertices allowed as intermediate

Note that $R^{(0)} = A$ (adjacency matrix), $R^{(n)} = T$ (transitive closure)



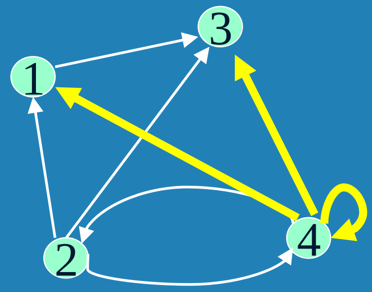
$R^{(0)}$

$$\begin{matrix} 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{matrix}$$



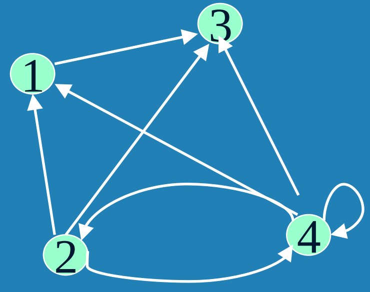
$R^{(1)}$

$$\begin{matrix} 0 & 0 & 1 & 0 \\ 1 & 0 & \mathbf{1} & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{matrix}$$



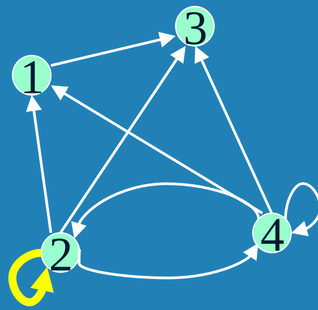
$R^{(2)}$

$$\begin{matrix} 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ \mathbf{1} & 1 & \mathbf{1} & \mathbf{1} \end{matrix}$$



$R^{(3)}$

$$\begin{matrix} 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 \end{matrix}$$



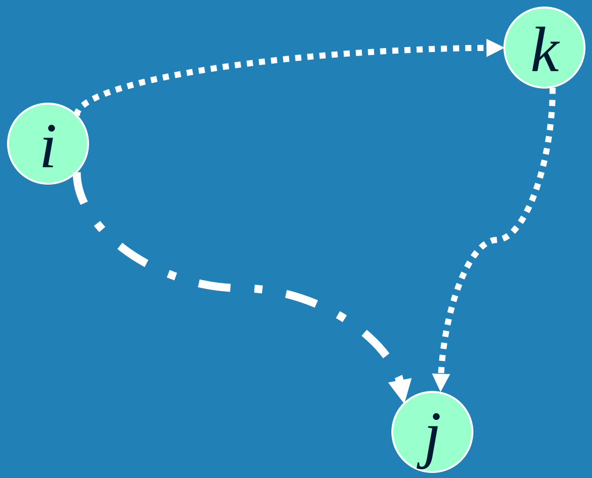
$R^{(4)}$

$$\begin{matrix} 0 & 0 & 1 & 0 \\ 1 & \mathbf{1} & 1 & 1 \\ 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 \end{matrix}$$

Warshall's Algorithm (recurrence)

On the *k*-th iteration, the algorithm determines for every pair of vertices *i, j* if a path exists from *i* and *j* with just vertices 1,…,*k* allowed as intermediate

$$R^{(k)}[i,j] = \begin{cases} R^{(k-1)}[i,j] & \text{(path using just } 1,\ldots,k\text{-1)} \\ \quad\text{or} & \\ R^{(k-1)}[i,k] \text{ and } R^{(k-1)}[k,j] & \text{(path from } i \text{ to } k \\ & \text{and from } k \text{ to } i \\ & \text{using just } 1,\ldots,k\text{-1)} \end{cases}$$



Warshall's Algorithm (matrix generation)

Recurrence relating elements $R^{(k)}$ to elements of $R^{(k-1)}$ is:

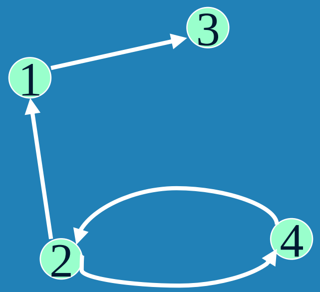
$$R^{(k)}[i,j] = R^{(k-1)}[i,j] \text{ or } (R^{(k-1)}[i,k] \text{ and } R^{(k-1)}[k,j])$$

It implies the following rules for generating $R^{(k)}$ from $R^{(k-1)}$:

Rule 1 If an element in row i and column j is 1 in $R^{(k-1)}$, it remains 1 in $R^{(k)}$

Rule 2 If an element in row i and column j is 0 in $R^{(k-1)}$, it has to be changed to 1 in $R^{(k)}$ if and only if the element in its row i and column k and the element in its column j and row k are both 1's in $R^{(k-1)}$

Warshall's Algorithm (example)



$$R^{(0)} = \begin{matrix} 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{matrix}$$

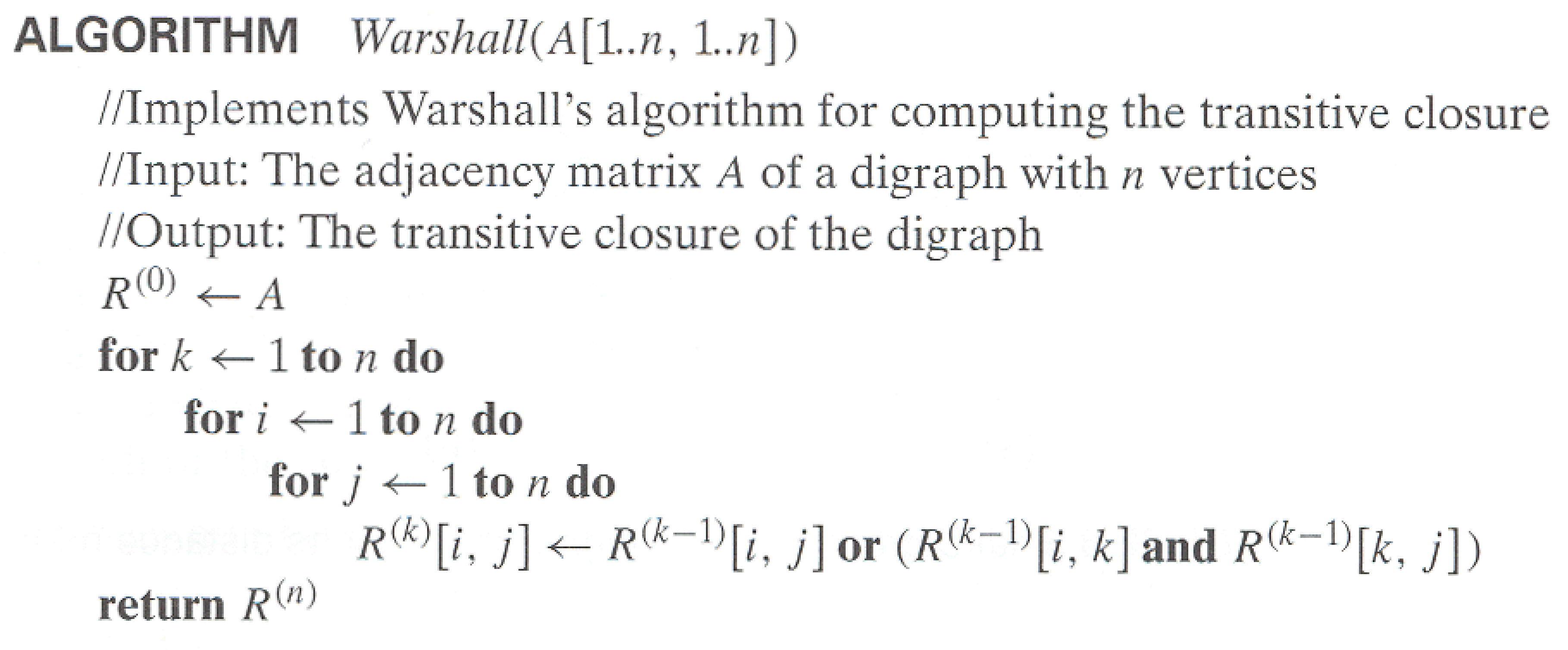
$$R^{(1)} = \begin{matrix} 0 & 0 & 1 & 0 \\ 1 & 0 & \mathbf{1} & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{matrix}$$

$$R^{(2)} = \begin{matrix} 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ \mathbf{1} & 1 & \mathbf{1} & \mathbf{1} \end{matrix}$$

$$R^{(3)} = \begin{matrix} 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 \end{matrix}$$

$$R^{(4)} = \begin{matrix} 0 & 0 & 1 & 0 \\ 1 & \mathbf{1} & 1 & 1 \\ 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 \end{matrix}$$

Warshall’s Algorithm (pseudocode and analysis)



```
ALGORITHM  Warshall(A[1..n, 1..n])
    //Implements Warshall’s algorithm for computing the transitive closure
    //Input: The adjacency matrix A of a digraph with n vertices
    //Output: The transitive closure of the digraph
    $R^{(0)} \leftarrow A$
    for $k \leftarrow 1$ to $n$ do
        for $i \leftarrow 1$ to $n$ do
            for $j \leftarrow 1$ to $n$ do
                $R^{(k)}[i, j] \leftarrow R^{(k-1)}[i, j]$ or $(R^{(k-1)}[i, k]$ and $R^{(k-1)}[k, j])$
    return $R^{(n)}$
```

Time efficiency: Θ(n^3)

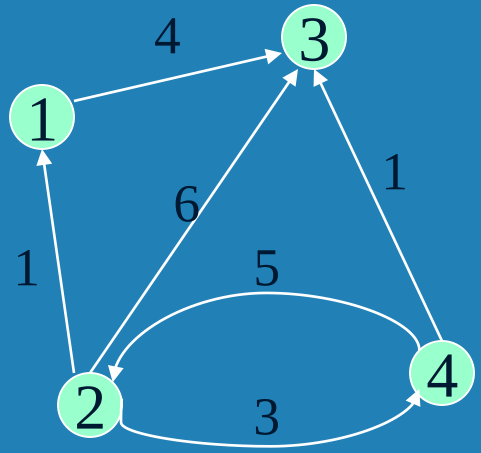
Space efficiency: Matrices can be written over their predecessors

Floyd's Algorithm: All pairs shortest paths

Problem: In a weighted (di)graph, find shortest paths between every pair of vertices

Same idea: construct solution through series of matrices $D^{(0)}, \ldots, D^{(n)}$ using increasing subsets of the vertices allowed as intermediate

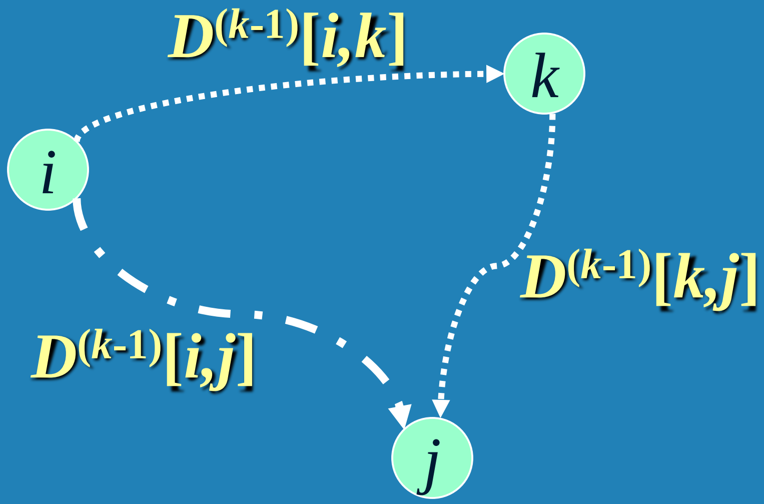
Example:



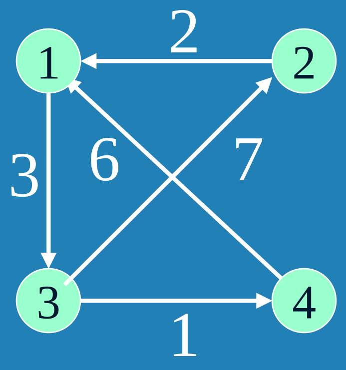
Floyd's Algorithm (matrix generation)

On the *k*-th iteration, the algorithm determines shortest paths between every pair of vertices *i, j* that use only vertices among 1,…,*k* as intermediate

$$D^{(k)}[i,j] = \min \{D^{(k-1)}[i,j],\ D^{(k-1)}[i,k] + D^{(k-1)}[k,j]\}$$



Floyd’s Algorithm (example)



$$D^{(0)} = \begin{matrix} 0 & \infty & 3 & \infty \\ 2 & 0 & \infty & \infty \\ \infty & 7 & 0 & 1 \\ 6 & \infty & \infty & 0 \end{matrix}$$

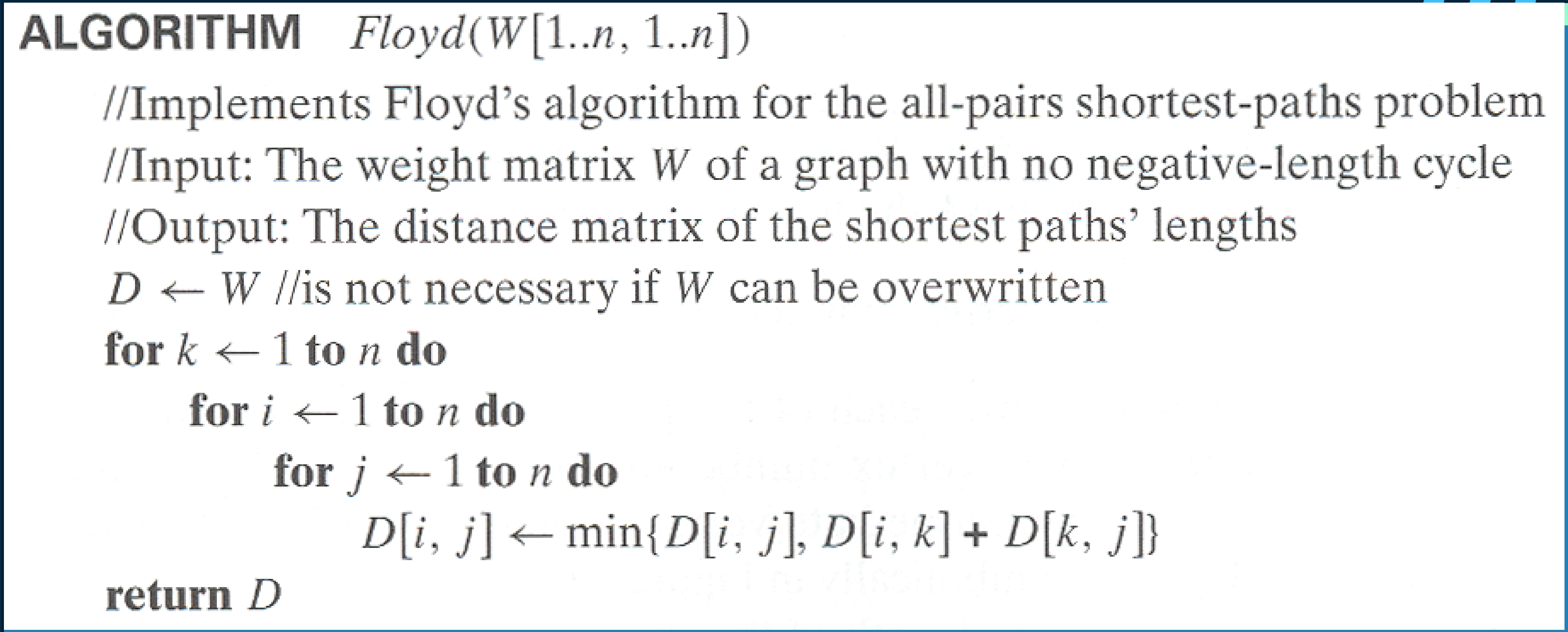
$$D^{(1)} = \begin{matrix} 0 & \infty & 3 & \infty \\ 2 & 0 & \mathbf{5} & \infty \\ \infty & 7 & 0 & 1 \\ 6 & \infty & \mathbf{9} & 0 \end{matrix}$$

$$D^{(2)} = \begin{matrix} 0 & \infty & 3 & \infty \\ 2 & 0 & 5 & \infty \\ \mathbf{9} & 7 & 0 & 1 \\ 6 & \infty & 9 & 0 \end{matrix}$$

$$D^{(3)} = \begin{matrix} 0 & \mathbf{10} & 3 & \mathbf{4} \\ 2 & 0 & 5 & \mathbf{6} \\ 9 & 7 & 0 & 1 \\ 6 & \mathbf{16} & 9 & 0 \end{matrix}$$

$$D^{(4)} = \begin{matrix} 0 & 10 & 3 & 4 \\ 2 & 0 & 5 & 6 \\ \mathbf{7} & 7 & 0 & 1 \\ 6 & 16 & 9 & 0 \end{matrix}$$

Floyd’s Algorithm (pseudocode and analysis)



```
ALGORITHM  Floyd(W[1..n, 1..n])
    //Implements Floyd’s algorithm for the all-pairs shortest-paths problem
    //Input: The weight matrix W of a graph with no negative-length cycle
    //Output: The distance matrix of the shortest paths’ lengths
    $D \leftarrow W$ //is not necessary if W can be overwritten
    for $k \leftarrow 1$ to $n$ do
        for $i \leftarrow 1$ to $n$ do
            for $j \leftarrow 1$ to $n$ do
                $D[i, j] \leftarrow \min\{D[i, j], D[i, k] + D[k, j]\}$
    return D
```

Time efficiency: Θ(n^3)

Space efficiency: Matrices can be written over their predecessors

Note: Shortest paths themselves can be found, too